

Research on Fractional Derivatives of Some Matrix Fractional Functions

Chii-Huei Yu

School of Mathematics and Statistics, Zhaoqing University, Guangdong, China

DOI: <https://doi.org/10.5281/zenodo.14177724>

Published Date: 18-November-2024

Abstract: In this paper, based on Jumarie type of R-L fractional derivative, we find arbitrary order fractional derivative of two types of matrix fractional functions. Fractional Leibniz rule and a new multiplication of fractional analytic functions play important roles in this article. Moreover, our results are generalizations of ordinary calculus results.

Keywords: Jumarie type of R-L fractional derivative, matrix fractional functions, fractional Leibniz rule, new multiplication, fractional analytic functions.

I. INTRODUCTION

Fractional calculus belongs to the field of mathematical analysis, involving the research and applications of arbitrary order integrals and derivatives. Fractional calculus originated from a problem put forward by L'Hospital and Leibniz in 1695. Therefore, the history of fractional calculus was formed more than 300 years ago, and fractional calculus and classical calculus have almost the same long history. Since then, fractional calculus has attracted the attention of many contemporary great mathematicians, such as N. H. Abel, M. Caputo, L. Euler, J. Fourier, A. K. Grunwald, J. Hadamard, G. H. Hardy, O. Heaviside, H. J. Holmgren, P. S. Laplace, G. W. Leibniz, A. V. Letnikov, J. Liouville, B. Riemann, M. Riesz, and H. Weyl. With the efforts of researchers, the theory of fractional calculus and its applications have developed rapidly. On the other hand, fractional calculus has wide applications in physics, mechanics, electrical engineering, viscoelasticity, biology, control theory, dynamics, economics, and other fields [1-16].

However, the definition of fractional derivative is not unique. Commonly used definitions include Riemann-Liouville (R-L) fractional derivative, Caputo fractional derivative, Grunwald-Letnikov (G-L) fractional derivative, Jumarie's modified R-L fractional derivative [17-21]. Because Jumarie type of R-L fractional derivative helps to avoid non-zero fractional derivative of constant function, it is easier to use this definition to connect fractional calculus with classical calculus.

In this paper, based on Jumarie type of R-L fractional derivative and a new multiplication of fractional analytic functions, we obtain arbitrary order fractional derivative of the following two types of matrix fractional functions:

$$E_{\alpha}(tAx^{\alpha}) \otimes_{\alpha} \cos_{\alpha}(tAx^{\alpha}),$$
$$E_{\alpha}(tAx^{\alpha}) \otimes_{\alpha} \sin_{\alpha}(tAx^{\alpha}),$$

where $0 < \alpha \leq 1$, t is a real number, and A is a matrix. Fractional Leibniz rule plays an important role in this article. In fact, our results are generalizations of classical calculus results.

II. PRELIMINARIES

Firstly, we introduce the fractional derivative used in this paper and its properties.

Definition 2.1 ([22]): Let $0 < \alpha \leq 1$, and x_0 be a real number. The Jumarie type of Riemann-Liouville (R-L) α -fractional derivative is defined by

$$({}_{x_0}D_x^{\alpha})[f(x)] = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dx} \int_{x_0}^x \frac{f(t)-f(x_0)}{(x-t)^{\alpha}} dt, \quad (1)$$

where $\Gamma(\cdot)$ is the gamma function. In addition, for any positive integer m , we define $(x_0 D_x^\alpha)^m [f(x)] = (x_0 D_x^\alpha)(x_0 D_x^\alpha) \cdots (x_0 D_x^\alpha)[f(x)]$, the m -th order α -fractional derivative of $f(x)$.

Proposition 2.2 ([23]): If α, β, x_0, C are real numbers and $\beta \geq \alpha > 0$, then

$$(x_0 D_x^\alpha)[(x - x_0)^\beta] = \frac{\Gamma(\beta+1)}{\Gamma(\beta-\alpha+1)}(x - x_0)^{\beta-\alpha}, \tag{2}$$

and

$$(x_0 D_x^\alpha)[C] = 0. \tag{3}$$

Next, the definition of fractional analytic function is introduced.

Definition 2.3 ([24]): If x, x_0 , and a_n are real numbers for all n , $x_0 \in (a, b)$, and $0 < \alpha \leq 1$. If the function $f_\alpha: [a, b] \rightarrow R$ can be expressed as an α -fractional power series, i.e., $f_\alpha(x^\alpha) = \sum_{n=0}^\infty \frac{a_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha}$ on some open interval containing x_0 , then we say that $f_\alpha(x^\alpha)$ is α -fractional analytic at x_0 . Furthermore, if $f_\alpha: [a, b] \rightarrow R$ is continuous on closed interval $[a, b]$ and it is α -fractional analytic at every point in open interval (a, b) , then f_α is called an α -fractional analytic function on $[a, b]$.

In the following, we introduce a new multiplication of fractional analytic functions.

Definition 2.4 ([25]): Let $0 < \alpha \leq 1$, and x_0 be a real number. If $f_\alpha(x^\alpha)$ and $g_\alpha(x^\alpha)$ are two α -fractional analytic functions defined on an interval containing x_0 ,

$$f_\alpha(x^\alpha) = \sum_{n=0}^\infty \frac{a_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha}, \tag{4}$$

$$g_\alpha(x^\alpha) = \sum_{n=0}^\infty \frac{b_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha}. \tag{5}$$

Then we define

$$\begin{aligned} & f_\alpha(x^\alpha) \otimes_\alpha g_\alpha(x^\alpha) \\ &= \sum_{n=0}^\infty \frac{a_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha} \otimes_\alpha \sum_{n=0}^\infty \frac{b_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha} \\ &= \sum_{n=0}^\infty \frac{1}{\Gamma(n\alpha+1)} \left(\sum_{m=0}^n \binom{n}{m} a_{n-m} b_m \right) (x - x_0)^{n\alpha}. \end{aligned} \tag{6}$$

Equivalently,

$$\begin{aligned} & f_\alpha(x^\alpha) \otimes_\alpha g_\alpha(x^\alpha) \\ &= \sum_{n=0}^\infty \frac{a_n}{n!} \left(\frac{1}{\Gamma(\alpha+1)}(x - x_0)^\alpha \right)^{\otimes_\alpha n} \otimes_\alpha \sum_{n=0}^\infty \frac{b_n}{n!} \left(\frac{1}{\Gamma(\alpha+1)}(x - x_0)^\alpha \right)^{\otimes_\alpha n} \\ &= \sum_{n=0}^\infty \frac{1}{n!} \left(\sum_{m=0}^n \binom{n}{m} a_{n-m} b_m \right) \left(\frac{1}{\Gamma(\alpha+1)}(x - x_0)^\alpha \right)^{\otimes_\alpha n}. \end{aligned} \tag{7}$$

Definition 2.5 ([26]): If $0 < \alpha \leq 1$, and $f_\alpha(x^\alpha)$, $g_\alpha(x^\alpha)$ are two α -fractional analytic functions defined on an interval containing x_0 ,

$$f_\alpha(x^\alpha) = \sum_{n=0}^\infty \frac{a_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha} = \sum_{n=0}^\infty \frac{a_n}{n!} \left(\frac{1}{\Gamma(\alpha+1)}(x - x_0)^\alpha \right)^{\otimes_\alpha n}, \tag{8}$$

$$g_\alpha(x^\alpha) = \sum_{n=0}^\infty \frac{b_n}{\Gamma(n\alpha+1)}(x - x_0)^{n\alpha} = \sum_{n=0}^\infty \frac{b_n}{n!} \left(\frac{1}{\Gamma(\alpha+1)}(x - x_0)^\alpha \right)^{\otimes_\alpha n}. \tag{9}$$

The compositions of $f_\alpha(x^\alpha)$ and $g_\alpha(x^\alpha)$ are defined by

$$(f_\alpha \circ g_\alpha)(x^\alpha) = f_\alpha(g_\alpha(x^\alpha)) = \sum_{n=0}^\infty \frac{a_n}{n!} (g_\alpha(x^\alpha))^{\otimes_\alpha n}, \tag{10}$$

and

$$(g_\alpha \circ f_\alpha)(x^\alpha) = g_\alpha(f_\alpha(x^\alpha)) = \sum_{n=0}^\infty \frac{b_n}{n!} (f_\alpha(x^\alpha))^{\otimes_\alpha n}. \tag{11}$$

Definition 2.6 ([27]): Let $0 < \alpha \leq 1$, and $f_\alpha(x^\alpha), g_\alpha(x^\alpha)$ be two α -fractional analytic functions. Then $(f_\alpha(x^\alpha))^{\otimes_\alpha n} = f_\alpha(x^\alpha) \otimes_\alpha \dots \otimes_\alpha f_\alpha(x^\alpha)$ is called the n -th power of $f_\alpha(x^\alpha)$.

Definition 2.7 ([28]): If $0 < \alpha \leq 1$, x is a real variable and A is a matrix. The matrix α -fractional exponential function, matrix α -fractional cosine function, and matrix α -fractional sine function are defined as follows:

$$E_\alpha(Ax^\alpha) = \sum_{n=0}^{\infty} A^n \frac{x^{n\alpha}}{\Gamma(n\alpha+1)} = \sum_{n=0}^{\infty} \frac{1}{n!} \left(A \frac{1}{\Gamma(\alpha+1)} x^\alpha \right)^{\otimes_\alpha n}, \quad (12)$$

$$\cos_\alpha(Ax^\alpha) = \sum_{n=0}^{\infty} A^{2n} \frac{(-1)^n x^{2n\alpha}}{\Gamma(2n\alpha+1)} = \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} \left(A \frac{1}{\Gamma(\alpha+1)} x^\alpha \right)^{\otimes_\alpha 2n}, \quad (13)$$

and

$$\sin_\alpha(Ax^\alpha) = \sum_{n=0}^{\infty} A^{2n+1} \frac{(-1)^n x^{(2n+1)\alpha}}{\Gamma((2n+1)\alpha+1)} = \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} \left(A \frac{1}{\Gamma(\alpha+1)} x^\alpha \right)^{\otimes_\alpha (2n+1)}. \quad (14)$$

Theorem 2.8 (fractional Leibniz rule): If $0 < \alpha \leq 1$, and $f_\alpha(x^\alpha), g_\alpha(x^\alpha)$ are two α -fractional analytic functions at $x = x_0$, then

$$({}_x D_x^\alpha)^m [f_\alpha(x^\alpha) \otimes_\alpha g_\alpha(x^\alpha)] = \sum_{k=0}^m \binom{m}{k} ({}_x D_x^\alpha)^{m-k} [f_\alpha(x^\alpha)] \otimes_\alpha ({}_x D_x^\alpha)^k [g_\alpha(x^\alpha)], \quad (15)$$

where $\binom{m}{k} = \frac{m!}{k!(m-k)!}$.

Definition 2.9: The smallest positive real number T_α such that $E_\alpha(iT_\alpha) = 1$, is called the period of $E_\alpha(ix^\alpha)$.

III. MAIN RESULTS

In this section, we use fractional Leibniz rule to find arbitrary order fractional derivative of two types of matrix fractional functions.

Theorem 3.1: If $0 < \alpha \leq 1$, t is a real number, m is a positive integer, A, E are matrices, and E is the unit matrix, then

$$({}_0 D_x^\alpha)^m [E_\alpha(tAx^\alpha) \otimes_\alpha \cos_\alpha(tAx^\alpha)] = (tA)^m \sum_{k=0}^m \binom{m}{k} E_\alpha(tAx^\alpha) \otimes_\alpha \cos_\alpha \left(tAx^\alpha + k \cdot \frac{T_\alpha}{4} E \right). \quad (16)$$

And

$$({}_0 D_x^\alpha)^m [E_\alpha(tAx^\alpha) \otimes_\alpha \sin_\alpha(tAx^\alpha)] = (tA)^m \sum_{k=0}^m \binom{m}{k} E_\alpha(tAx^\alpha) \otimes_\alpha \sin_\alpha \left(tAx^\alpha + k \cdot \frac{T_\alpha}{4} E \right). \quad (17)$$

Proof Using fractional Leibniz rule yields

$$\begin{aligned} &({}_0 D_x^\alpha)^m [E_\alpha(tAx^\alpha) \otimes_\alpha \cos_\alpha(tAx^\alpha)] \\ &= \sum_{k=0}^m \binom{m}{k} ({}_x D_x^\alpha)^{m-k} [E_\alpha(tAx^\alpha)] \otimes_\alpha ({}_x D_x^\alpha)^k [\cos_\alpha(tAx^\alpha)] \\ &= \sum_{k=0}^m \binom{m}{k} (tA)^{m-k} E_\alpha(tAx^\alpha) \otimes_\alpha (tA)^k \cos_\alpha \left(tAx^\alpha + k \cdot \frac{T_\alpha}{4} E \right) \\ &= (tA)^m \sum_{k=0}^m \binom{m}{k} E_\alpha(tAx^\alpha) \otimes_\alpha \cos_\alpha \left(tAx^\alpha + k \cdot \frac{T_\alpha}{4} E \right). \end{aligned}$$

And

$$\begin{aligned} &({}_0 D_x^\alpha)^m [E_\alpha(tAx^\alpha) \otimes_\alpha \sin_\alpha(tAx^\alpha)] \\ &= \sum_{k=0}^m \binom{m}{k} ({}_x D_x^\alpha)^{m-k} [E_\alpha(tAx^\alpha)] \otimes_\alpha ({}_x D_x^\alpha)^k [\sin_\alpha(tAx^\alpha)] \\ &= \sum_{k=0}^m \binom{m}{k} (tA)^{m-k} E_\alpha(tAx^\alpha) \otimes_\alpha (tA)^k \sin_\alpha \left(tAx^\alpha + k \cdot \frac{T_\alpha}{4} E \right) \\ &= (tA)^m \sum_{k=0}^m \binom{m}{k} E_\alpha(tAx^\alpha) \otimes_\alpha \sin_\alpha \left(tAx^\alpha + k \cdot \frac{T_\alpha}{4} E \right). \end{aligned} \quad \text{q.e.d.}$$

IV. CONCLUSION

In this paper, based on Jumarie type of R-L fractional derivative and a new multiplication of fractional analytic functions, we use fractional Leibniz rule to obtain arbitrary order fractional derivative of two types of matrix fractional functions. Moreover, our results are generalizations of traditional calculus results. In the future, we will continue to use our methods to study the problems in engineering mathematics and fractional differential equations.

REFERENCES

- [1] A. Carpinteri, F. Mainardi, *Fractals and Fractional Calculus in Continuum Mechanics*, Springer, New York, 1997.
- [2] J. Sabatier, O. P. Agrawal, J.A. Tenreiro Machado, *Advances in Fractional Calculus. Theoretical Developments and Applications in Physics and Engineering*, Springer, Dordrecht, 2007.
- [3] V. E. Tarasov, Review of Some Promising Fractional Physical Models, *International Journal of Modern Physics*, vol. 27, no. 9, 2013.
- [4] Mohd. Farman Ali, Manoj Sharma, Renu Jain, An application of fractional calculus in electrical engineering, *Advanced Engineering Technology and Application*, vol. 5, no. 2, pp. 41-45, 2016.
- [5] J. T. Machado, *Fractional Calculus: Application in Modeling and Control*, Springer New York, 2013.
- [6] E. Soczkiewicz, Application of fractional calculus in the theory of viscoelasticity, *Molecular and Quantum Acoustics*, vol.23, pp. 397-404, 2002.
- [7] F. Mainardi, Fractional calculus: some basic problems in continuum and statistical mechanics, *Fractals and Fractional Calculus in Continuum Mechanics*, pp. 291-348, Springer, Wien, Germany, 1997.
- [8] R. Magin, Fractional calculus in bioengineering, part 1, *Critical Reviews in Biomedical Engineering*, vol. 32, no.1, pp.1-104, 2004.
- [9] V. E. Tarasov, Mathematical economics: application of fractional calculus, *Mathematics*, vol. 8, no. 5, 660, 2020.
- [10] H. A. Fallahgoul, S. M. Focardi and F. J. Fabozzi, *Fractional calculus and fractional processes with applications to financial economics, theory and application*, Elsevier Science and Technology, 2016.
- [11] M. F. Silva, J. A. T. Machado, and I. S. Jesus, Modelling and simulation of walking robots with 3 dof legs, in *Proceedings of the 25th IASTED International Conference on Modelling, Identification and Control (MIC '06)*, pp. 271-276, Lanzarote, Spain, 2006.
- [12] M. Teodor, Atanacković, Stevan Pilipović, Bogoljub Stanković, Dušan Zorica, *Fractional Calculus with Applications in Mechanics: Vibrations and Diffusion Processes*, John Wiley & Sons, Inc., 2014.
- [13] C. -H. Yu, A study on fractional RLC circuit, *International Research Journal of Engineering and Technology*, vol. 7, no. 8, pp. 3422-3425, 2020.
- [14] C. -H. Yu, A new insight into fractional logistic equation, *International Journal of Engineering Research and Reviews*, vol. 9, no. 2, pp.13-17, 2021.
- [15] R. Hilfer (Ed.), *Applications of Fractional Calculus in Physics*, WSPC, Singapore, 2000.
- [16] F. Duarte and J. A. T. Machado, Chaotic phenomena and fractional-order dynamics in the trajectory control of redundant manipulators, *Nonlinear Dynamics*, vol. 29, no. 1-4, pp. 315-342, 2002.
- [17] I. Podlubny, *Fractional Differential Equations*, Academic Press, San Diego, Calif, USA, 1999.
- [18] K. B. Oldham and J. Spanier, *The Fractional Calculus*, Academic Press, Inc., 1974.
- [19] K. S. Miller and B. Ross, *An introduction to the Fractional Calculus and Fractional Differential Equations*, A Wiley-Interscience Publication, John Wiley & Sons, New York, USA, 1993.
- [20] S. Das, *Functional Fractional Calculus for System Identification and Control*, 2nd ed., Springer-Verlag, Berlin, 2011.
- [21] K. Diethelm, *The Analysis of Fractional Differential Equations*, Springer-Verlag, 2010.

- [22] C. -H. Yu, Study of fractional analytic functions and local fractional calculus, International Journal of Scientific Research in Science, Engineering and Technology, vol. 8, no. 5, pp. 39-46, 2021..
- [23] C. -H. Yu, Study of fractional analytic functions and local fractional calculus, International Journal of Scientific Research in Science, Engineering and Technology, vol. 8, no. 5, pp. 39-46, 2021.
- [24] C. -H, Yu, Fractional partial differential problem of some matrix two-variables fractional functions, International Journal of Mechanical and Industrial Technology, vol. 12, no. 2, pp. 6-13, 2024.
- [25] C. -H, Yu, Study of two matrix fractional integrals by using differentiation under fractional integral sign, International Journal of Civil and Structural Engineering Research, vol. 12, no. 2, pp. 24-30, 2024.
- [26] C. -H, Yu, Study of some type of matrix fractional integral, International Journal of Recent Research in Civil and Mechanical Engineering, vol. 11, no. 2, pp. 5-8, 2024.
- [27] C. -H, Yu, Evaluating fractional derivatives of two matrix fractional functions based on Jumarie type of Riemann-Liouville fractional derivative, International Journal of Engineering Research and Reviews, vol. 12, no. 4, pp. 39-43, 2024.
- [28] C. -H, Yu, Studying three types of matrix fractional integrals, International Journal of Interdisciplinary Research and Innovations, vol. 12, no. 4, pp. 35-39, 2024.